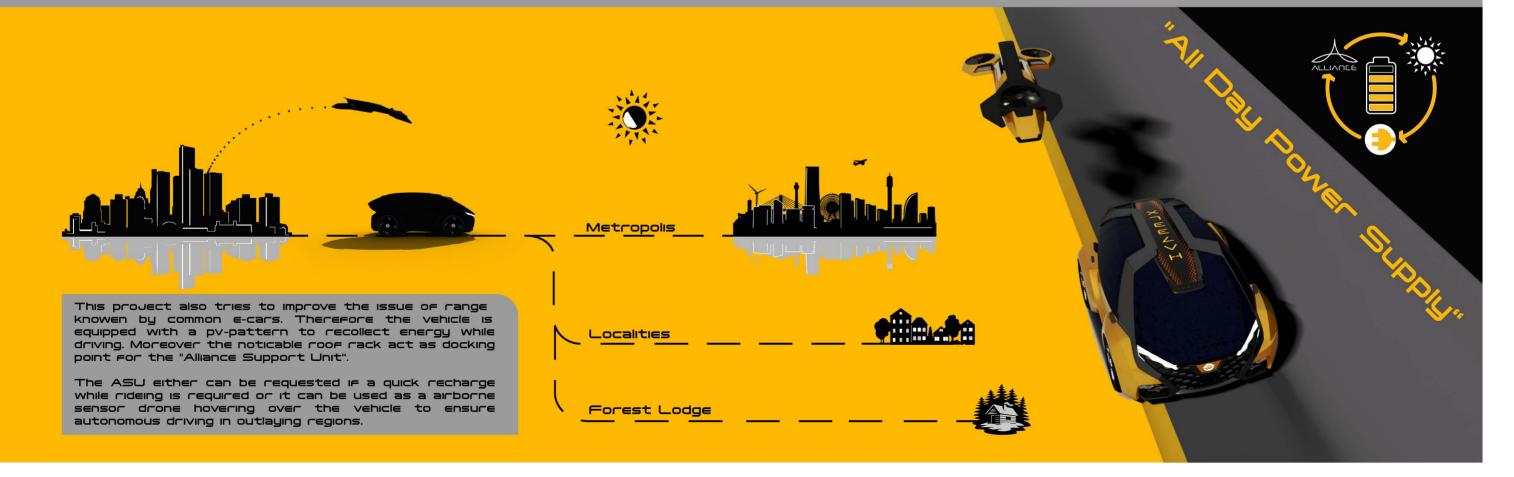


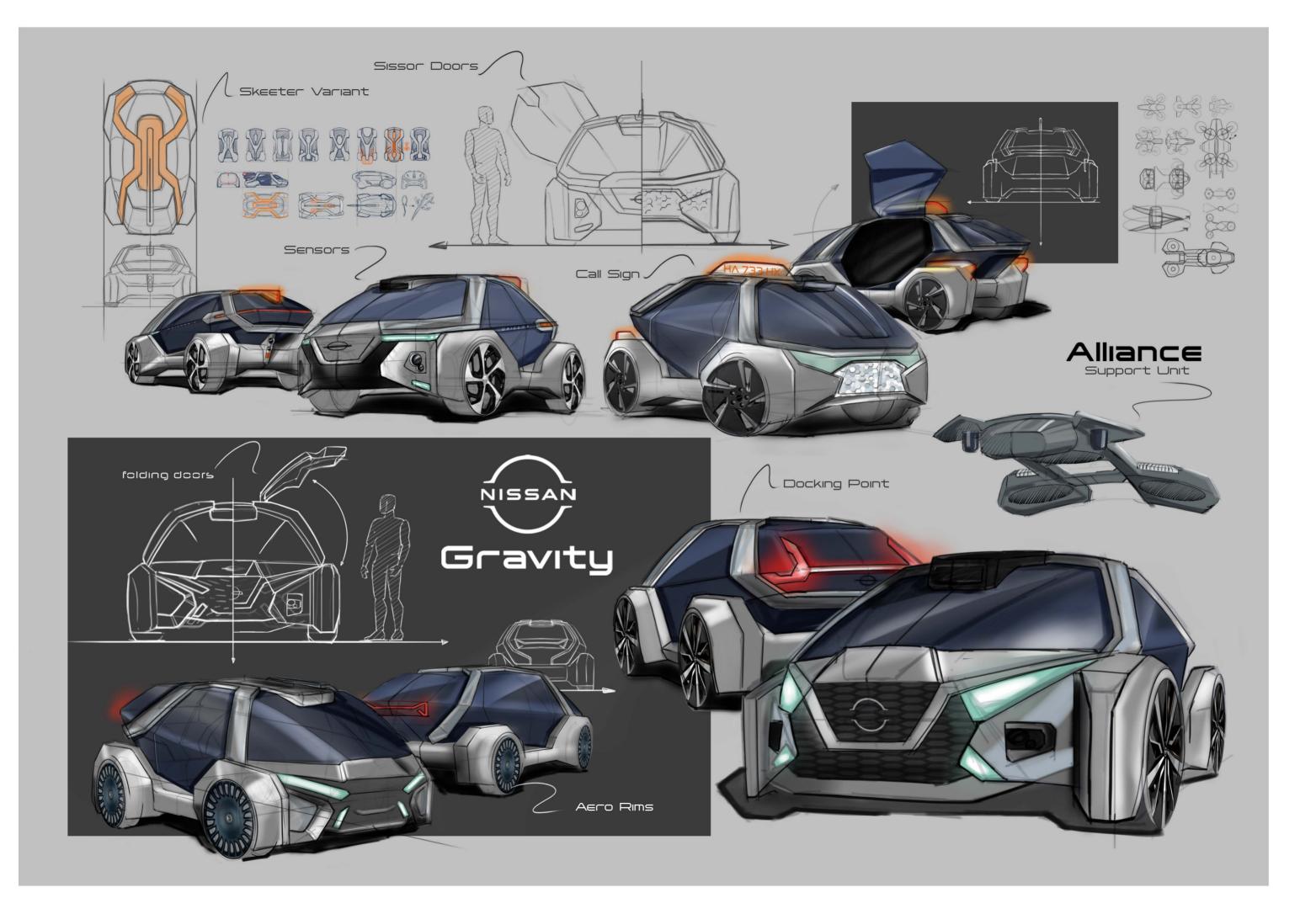
Gravity and its Alliance drone programm are an autonomous driving concept which aims to expand prospective autonomous range.

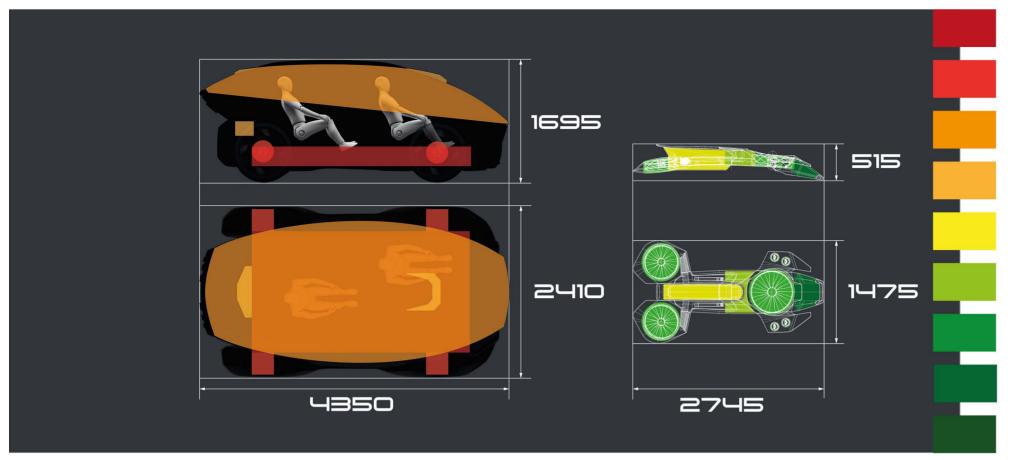
Based on a collective intelligence every vehicle is still able to act as a independent unit. Although a superior connection with its surroundings is recomended, its not necessary to work properly. Moreover it is even possible to operate in autonomous unchartered regions.

Gravity is developed for people with special needs, espacially those which want to travel just in time without annoying, time consuming, recharge stops.
This Concept allows you to travel further than before, while focusing on what you prefer mostly. Regardless if you have to work, sleep or just enjoy onboard entertainment.

Even trough the onboard monitor system the interior is made to fulfill the demands of 2-3 passangers. While enjoying complete privacy through the non transparent cockpit the passangers can decide if they want to follow the journey, watching a movie or sleep without disturbing daylight,







Main Battery

Electric Hub Engine

PV-Surface/ Onboard Monitor

Multiple Sensors

External Powerpack

Main Battery

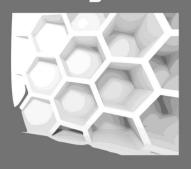
Multiple Sensors

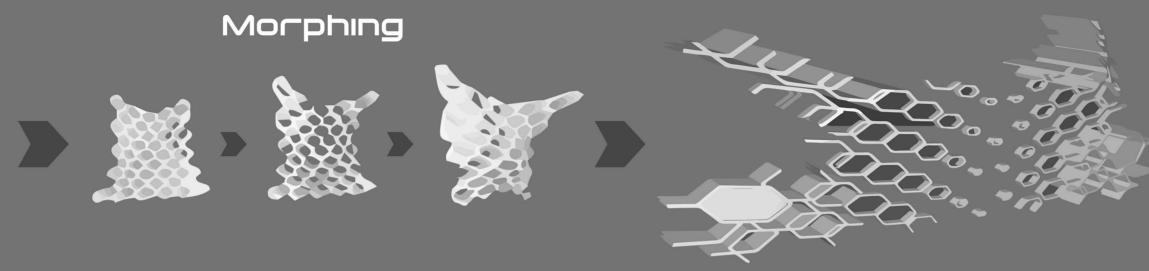
Airborne Computer

Multiple Sensors



Honeycomb







Hidden Lights

The design for the frontend was originally inspired by the concept of hidden lights and a hexagonal honeycomb grid. With Alias and its plugin Dynamo, I have created my own version for the Gravity project.

The wheels with its rims are also kind of special. They are mounted in a special way directly on the electric nut engine. That way, the illuminated manufacturers sign can be read to every time.













